# MULTIAXISFORCESENSOR

## Tec Gihan



FORCE PLATE TREDMILL HAPTICS

## **ABOUT US**

Measuring Invisible Forces

We are a Japan-based manufacturer of force sensors, and since our founding in 1991 we have placed measurement at the heart of our work. In addition to sensor development, we maintain amplifiers, data processing, and software in-house, cultivating strong core technologies. We continue to develop new technologies and take on what remains unknown in this world.

High-Precision Sensor Manufacturing

Designing compact multi-axis force sensors is one of our core competencies. We also excel at developing force plates that leverage multi-axis sensors. These products are not defined by design alone—precise calibration is critical We develop proprietary calibration rigs to ensure accuracy and deliver high-precision sensors. We also specialize in custom designs and can meet a wide range of needs.

Electronic Circuit

Design

Sensor Design

Mechanical Design

Tec Gihan

Software Design

Technical Sales Engineer

Own Factory

### Main Fields

Academia

Industrial R&D

Automotive

Military

Hospitals

Biomechanics

Robotics

Ergonomics

Haptics

Mechanical Engineering

Healthcare

Rehabilitation

## 3-Axis Force Fx Fy Fz













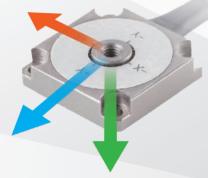
USX10-H10

500/1.5K N



TL6F04

2K/5K N



A compact, low-profile multi-axis force sensor that integrates easily into a wide range of applications. We have extensive experience with bespoke designs and customizations and can tailor the sensor to your exact requirements.





















Torque Mz



0.5/10/50/150 Nm

Name	Sma	all 3-axis For	ce Sensor / 2	?-axis Mome	nt Sensor		Small 3-axis Ford	ce Sensor	High-Sensitivity Small 3-axis Fo		Small 3-axis Fo	orce Sensor	Small 6-axis Force	e Sensor	6-axis Force	e Sensor	2-axis Moment Sensor		Small Torque	Sensor	
Model	USL06-H5-50N	**-100N	**-200N	**-500N	**-0.9NM	**-1.4NM	USL08-H6-1KN	**-2KN	USLG25-10N	USLG10-10N	TL3B05	TL3B04	USX10-H10-500N	**-1.5KN	TL6F04-2KN	**-5KN	TL2F14-12NM	TTQ06-0.5NM	**-10NM	**-50NM	**-150NM
Rated Capacity Fx, Fy	± 25N	± 50N	± 100N	± 250N	<u> </u>		± 500N	± 1000N	± 10N	± 10N	± 250N	± 2500N	± 250N	± 750N	± 2000N	± 2500N	_	_	_		
Fz	+50N	+100N	+ 200N	+ 500N		<del></del>	+1000N	+2000N	+10N	+ 10N	+500N	+ 5000N	+500N	+1500N	+2000N	± 5000N	<u> </u>	<u> </u>	<del></del>	<u> </u>	<u> </u>
Mx, My		_		_	± 0.9NM	± 1.4NM		_	_	_	_	_	± 4NM	± 12NM	± 70NM	± 70NM	± 12NM	_	_		
Mz	<del></del>	<u> </u>		—	<u> </u>	—	<del></del>	_	<del></del>	<del></del>	—	<u> </u>	±2NM	± 6NM	± 70NM	± 70NM	<u> </u>	± 0.5NM	± 10NM	± 50NM	± 150NM
Allowable Overload		2009	%		15	0%	120%		150%	200%	150%	150%	150%		150%	130%	150%		150%	, ,	
Nonlinearity			≦±1%R.	.0.			≦±1%R.	.0.	≦±1%R.O.	≦±1%R.O.	≦±1%R.O.	≦±1%R.O.	≦±1%R.0	).	≦±1%	R.O.	≦±0.5%R.O.		≦±0.5%	R.O.	
Hysteresis			≦±1%R.	.O.			≦±1%R	.0.	≦±1%R.O.	≦±1%R.O.	≦±1%R.O.	≦±1%R.O.	≦±1%R.0	).	≦±1%	R.O.	≦±0.5%R.O.		≦±0.5%	R.O.	
Cross-talk			≦±1%R.	.0.			≦±1%R.	.0.	Fx,y:≦±1%R.O. Fz:≦±2%R.O.	≦±2%R.O.	≦±1%R.O.	≦±1%R.O.	≦±1%R.0	Э.	≦±2%	R.O.	≦±1%R.O.				
Dimensions (W×D×H)			20×20×51	mm			28×28×6	mm	Φ25×28mm	Ф14×27mm	Φ42×45mm	Ф 48 × 40mm	30×30×10r	mm	Φ48×40	Omm	Ф40×40mm	Ф38×22mm	Ф38×30	Ф40×30	Φ49×35
Weight(excl.cables)		3g		7g	3g	9g	20g		22g	12g	60g	75g	15g	40g	75g		78g	49g	61g	130g	210g
Others	USL06-AP Mod Power-supply Unloaded outp Output: (Unlo	voltage : 5V ± out : Approx. 2	2.5V (Initial ad	djustment by	fixed resistand	ce)															

# Strain-Gauge Amplifier / AD Converter / Data Logger



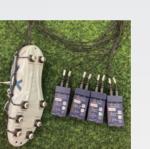
We offer amplifiers tailored to your application.

Some models are optimized to perform built-in cross-axis (crosstalk) compensation for multi-axis sensors, so you can use your sensors right away. Custom designs are also available.















Strain-Gauge **Amplifier** 













DMA-03

DPA-03

DPA-06

PDL-06-SA

Name	3ch Signal Conditioner (Analog Amplifier)	Compact 3ch Digital Amplifier	Compact 3ch Operational Amplifier	Compact 6ch Operational Amplifier (Analog / Digital)	Portable 6ch Digital Amplifier (with Data Logger)
Model	DSA-03	DMA-03	DPA-03	DPA-06	PDL-06-SA
Number of Channels	3 ch	3 ch	3 ch	6 ch	6 ch
Applied voltage	DC 2.5 V	DC 2 V	DC 2 V	DC 2 V	DC 2 V
Sampling frequency	Analog output only	1 ~ 1000 Hz	Analog output only	1 ~ 10000 Hz	SD card recording : 500 or 1000 Hz PC recording : 10 ~ 100 Hz
Measurement range	±500 / ±1000 / ±2000 / ±5000 με	±5000 με	±250 / ±500 / ±1000 / ±2000 / ±5000 με	$\pm 7000\mu\varepsilon$ (incl. zero adjustment range)	$\pm5000\mu\varepsilon$ (incl. zero adjustment range)
Resolution	Analog output only	16 bit	Analog output only	16 bit	16 bit
Analog output	±5 V	None	±5 V	±10V	None
Cross-talk Compensation	None	Available	Available	Available	Available
Dimensions (W×D×H)	30 × 128.5 × 191 mm	77 × 25× 71.5 mm	24 × 70 × 72 mm	120 × 105 × 30 mm	83.5 × 45 × 23.9 mm
Weight	620 g	190 g	165 g	340 g	64 g
Others	· TRIG : None	TRIG : A point of contact     Maximum 10 devices	· TRIG : None	TRIG : A point of contact     Maximum 20 devices	• TRIG : Infrared • Battery Charging Time : 2hours Operating Time : 1.5hours

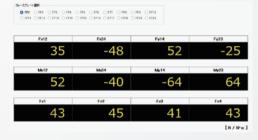
#### **AD** Converter



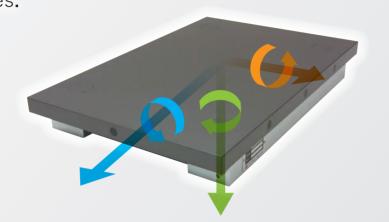
DSS300-HR

Name	12ch AD Converter
Model	DSS300-HR
Number of Channels	12 ch
Input voltage	± 10 V
Sampling frequency	1 ~ 20000 Hz
Resolution	16 bit
Cross-talk Compensation	Available
Dimensions (W×D×H)	228 × 110 × 55 mm
Weight	1000 g
Others	Includes control software     TRIG : A point of contact 、TTL     Maximum 8 devices

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For installation, we monitor the load distribution on each sensor to ensure balanced loading and stable, reliable measurements.













TF-2020 10 N ▶To P13



M3D 1000 N ▶To P16



TF-3020 1000 N



TF-3040 1000 N



TFG-4060 3000 N



TF-4060 10000 N



TF-4060-G 10000 N



TF-6090 10000 N



TF-90100 10000 N

09





Name	Compact Force Plate	Compact Force Plate	Portable Force Plate	Standard Force Plate	Big Force Plate	Gaint Force Plate	Glass Force Plate
Model	TF-3020	TF-3040	TFG-4060	TF-4060	TF-6090	TF-90100	TF-4060-G
Rated Capacity Fx, Fy	± 300 N	± 300 N	± 1000 N	± 3000 N	± 3000 N	± 3000 N	± 3000 N
Fz	+1000 N	+ 1000 N	+ 3000 N	+ 10000 N	+ 10000 N	+ 10000 N	+ 10000 N
Mx	± 60 Nm	± 150 Nm	± 600 Nm	± 2000 Nm	± 3500 Nm	± 3500 Nm	± 2000 Nm
My	± 100 Nm	± 100 Nm	± 450 Nm	± 1500 Nm	± 2500 Nm	± 3000 Nm	± 1500 Nm
Mz	± 60 Nm	± 60 Nm	± 200 Nm	± 600 Nm	± 900 Nm	± 1000 Nm	± 600 Nm
Allowable Overload	150 %	150 %	150 %	150 %	150 %	150 %	120 %
Nonlinearity	≦±1%R.O.	≤±1%R.O.	≦±1%R.O.	≤±0.5%R.O.	≦±0.5%R.O.	≦±1%R.O.	≦±1%R.O.
Hysteresis	≦±1%R.O.	≦±1%R.O.	≦±1%R.O.	≦±0.5%R.O.	≦±0.5%R.O.	≦±1%R.O.	≦±1%R.O.
Cross-talk	≦±2%R.C.	≦ ± 2 % R.C.	≦±2%R.C.	≦±1%R.C.	≦±1%R.C.	≦±2%R.C.	≦ ± 2 % R.C.
Natural Frequency	Z : 720 Hz	X,Y:600 / Z:320 Hz	X,Y:550 / Z:200 Hz	X,Y:360 / Z:420 Hz	X,Y:280 / Z:350 Hz	X,Y:220 / Z:340 Hz	X,Y:300 / Z:370 H
Dimensions (W×D×H)	300 × 200 × 46 mm	300 × 400 × 44 mm	400 × 600 × 50 mm	400 × 600 × 77 mm	600 × 900 × 100 mm	900 × 1000 × 130 mm	400 × 600 × 97 mm
Weight	4 kg	7 kg	14 kg	31 kg	48 kg	68 kg	29 kg
Others	Separate amplifier     Analog output available	Integrated amplifier     Analog output available	Separate amplifier     Analog output available				

08

The high-performance treadmill features a built-in force plate, enabling repeated measurement of ground reaction forces during walking and running. Thanks to advanced design and calibration technology, it provides high-precision data acquisition.





It is equipped with control software that enables independent belt control and programmable operation. By applying force feedback to the belt based on braking and propulsive forces, it reproduces natural walking, running, and uphill/downhill movement.

#### Single Belt Model



During running, there is no double-support phase—contact alternates between single-foot stance and a flight phase—so a single force plate is sufficient for measurement. You can focus on running without worrying about the belt seam. In load-control mode, deliberately applying a high load enables training that simulates uphill running or tire-drag pulls.

#### Dual Belt Model

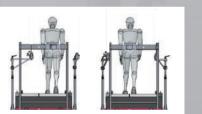


During walking, there are moments when both feet contact the treadmill; however, because the dual-belt model places independent force plates (FPs) under the left and right belts, it can acquire six-component ground-reaction force and moment data (Fx, Fy, Fz, Mx, My, Mz) for each side. Since the left and right belt speeds can be controlled independently, the system is well suited for rehabilitation and for assistive suit (exoskeleton) development.

#### Hybrid Model



By simply adjusting the handrail position, this hybrid model supports both single-belt and dual-belt configurations.













(\* These are approximate dimensions and do not include any protruding parts.)

Force Plate			
Rated Capacity	Fx, Fy: ±3000 N / Fz: +6000 N	Fx , Fy : ±3000 N / Fz : +6000 N	600mm Belt Side : Same as HPT-2200S
	Mx: ±3000 Nm / My, Mz: ±1500 Nm	Mx: ±3000 Nm / My: ±1000 Nm /Mz: ±1500 Nm	400mm Belt Side : Same as HPT-2200D
Allowable Overload	150 %	150 %	150 %
Nonlinearity	≤±1%R.O.	≦±1%R.O.	≦±1%R.O.
Hysteresis	≦±1%R.O.	≦±1%R.O.	≦±1%R.O.
Cross-talk	≦±2%R.C.	≦±2%R.C.	≦±2%R.C.

Optional function

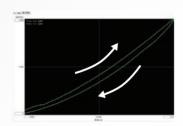
- · Force Feedback Belt Control Mode
- External Voltage-Controlled Belt Drive Mode
- VR System

- · External camera sync function
- Suspension Mechanism

#### **YAWASA**

#### **Indentation Tester for Soft Materials**

This is an indentation tester for soft (low-modulus) materials. Equipped with high-sensitivity force sensors (5 N or 50 N), it indents at a constant speed and, upon reaching the preset load setpoint, returns at a constant speed.



It measures the force-displacement (F-S) curve in both directions and calculates metrics such as Young's modulus, stiffness (slope), hysteresis, and energy (work).

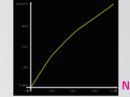
## Haptic skill logger

A finger-worn device that measures fingertip pressing (normal) force. Because the fingerprint remains exposed, you can measure without compromising the natural feel of the object. The sensor comes in five sizes, with measurement ranges up to 20-30 N (depending on size).













## Your finger becomes the sensor.

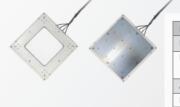
## **Yubi-Reco**

It enables quantitative evaluation of tactile feel and sharing of haptic sensations. By wrapping a PVDF (polyvinylidene fluoride) piezoelectric film around the finger, it captures vibrations introduced through the fingertip—turning your finger into a vibration sensor.







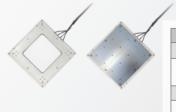


Traine	Compact Force Flate
Model	TF-2020
Rated Capacity Fx, Fy, Fz	± 10 N
Mx, My, Mz	± 0.8 Nm
Allowable Overload	200 %
Nonlinearity	≦±1%R.O.
Hysteresis	≦±1%R.O.
Cross-talk	≦±2%R.C.
Natural Frequency	X:190 / Y:190 / Z:270 Hz
Dimensions $(W \times D \times H)$	300 × 200 × 46 mm
Weight	4 kg
Others	· Separate amplifier
	· Analog output available

### **TF-2020**

#### Haptic Force Plate

An ultra-sensitive force plate that captures even feather-touch loads while measuring all six components (Fx, Fy, Fz, Mx, My, Mz). It visualizes how forces are applied when handling delicate objects and enables textile evaluation from a haptics (tactile) perspective.



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## Geometry Sensing System SEAT TRACER

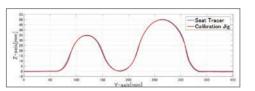


# SEAT TRACER

## Acuracy

Shipped only after verifying a root-mean-square error (RMSE) of  $\leq$  0.5 mm.





An innovative flexible sensor equipped with a 3-axis accelerometer and a 3-axis gyroscope that dynamically (i.e., non-static) measures the otherwise invisible three-dimensional geometry of a seat while a person is seated. It can be applied not only to automotive seats but also to mattresses with cushioning materials and office chairs.

Type : ST2-2040C-1

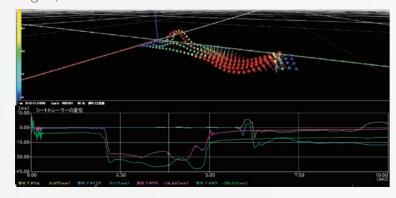
Type: ST2-2040D-1

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## tware

#### Data Analytics

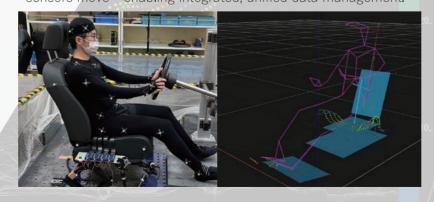
From the 3D data acquired with the Seat Tracer, you can compute and visualize displacement, point-to-point distances, angles, and other relative measurements.



## Stryare

#### Integrataed Motion Capture

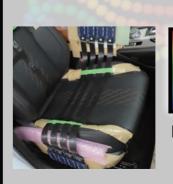
By measuring simultaneously with motion capture, the Seat Tracer data can be aligned to a common coordinate system—even if the sensors move—enabling integrated, unified data management.

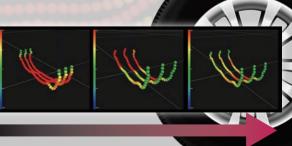


### Vgg-Ou

#### Dynamic Mode

We refined our acceleration-noise cancellation algorithm, enabling measurements even during real-vehicle driving.





before

## Mini Force Plate

M3D-EL-FP



Pedal Force Plate



A wearable, foot-mounted force plate that overturns the notion that force plates must be floor-installed.

Attached to the sole, it enables measurements without being limited by the measurement area and can also be mounted on pedals.

Available in wired, wireless, and analog-output models



Name		Mini Force Plate	Mini Force Plate
Model		M3D-EL-FP-80 · M3D-EL-FP-95	Pedal Force Plate
Rated Capacity	Fx, Fy	± 500 N	± 200 N
	Fz	+1000 N	+100 N
	Mx, My	± 30 Nm	± 0.4 Nm
	Mz	± 15 Nm	± 0.2 Nm
Allowable Overlo	ad	150 %	150 %
Nonlinearity		≦±1%R.O.	≦±1%R.O.
Hysteresis		≤±1%R <u>.</u> O.	≦±1%R.O.
Dimensions (W	×D×H)	□80type : 80 × 80 × 11 mm □95type : 95 × 95 × 11 mm	60 × 60 × 9.5 mm
Weight		□80type: 150 g □95type: 170g	170g
Others		M3D-EL-FP-W : Wireless Model     M3D-EL-FP-U : Wired Model     M3D-EL-FP-A : Analog Output Model     *Separate amplifiier	· Separate amplifiier

## Systems for Automotive Development

## Streering Sensor

While maintaining the wheel's natural shape, it enables detailed measurement of driver-applied forces. By integrating USL06 sensors into both the front and rear faces of the steering wheel, it measures not only torque but also grip force and opposing inputs—i.e., forces that cancel each other out in torque.





Name	Streering Sensor
Sensor	USL06-H5-100N ×20unit
	*Available rated capacities: 50 / 200 / 500N
Dimensions	Handle diameter : approx. Φ380 mm
	Handle thickness : approx. Ф30 mm
Interface	USB connection (digital)
	BNC connector (analog output ±10 V)
	ZERO balance button
	REC start button
Optional Items	Boss 6-axis Force Sensor
o p ===================================	

## **IMU Sensor**

## 9-axis Motion Sensor IMSSD

A compact, high-precision IMU sensor.

It supports high-speed sampling and logging at 1000 Hz to the built-in SD card. It also features a standalone mode that starts recording with a single switch.



3-axis Accelerometer

3-axis Gyroscope

3-axis Magnetometer

SDcard 1000Hz logging!

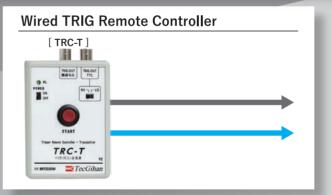


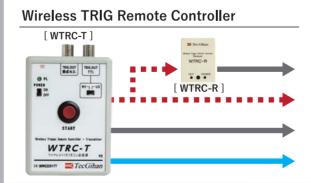




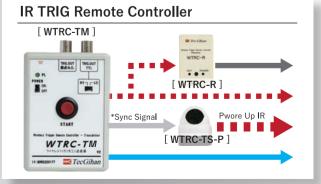
Name	9-axis motion sensor
Model	IMSSD-H-A
Sensor Specifications	
Acceleration	±4G/±8G/±16G/±30G · 16bit
Angular Velocity	± 4000 deg/s · 16bit
Magnetic Field	±300 μ T · 12bit
Sampling Rates	SD Card Recording: up to 1000 Hz
	PC Recording (via Bluetooth): up to 100 Hz
TRIG	Infrared TRIG IN
Battery	
Charging Time	Approximately 2.5 hours
Continuous Operating Time	Approximately 2.5 hours
Dimensions (W×D×H)	54 × 42 × 14 mm
Weight	30 g
Others	Connectivity:
	Up to 20 units can be connected

## Trigger Unit





Contact Closure



Wired ANALOG TRIG Remote Controller

[TRC-T-ON/OFF]

TRC-T-ON/OFF

TTL(UP or DOWN)

IR Signal

\*Switches with each button press

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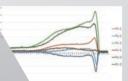
Simply connect the force plate to a tablet via USB to instantly overlay resultant force vectors on the video. It can report metrics such as peak force and acceleration, providing immediate feedback. Data can also be recorded at

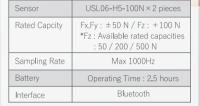
#### Ball Sensor

By embedding the USL06 in the ball, the release-phase forces acting on the fingers during pitching can be measured in three components



















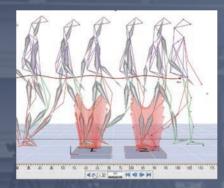


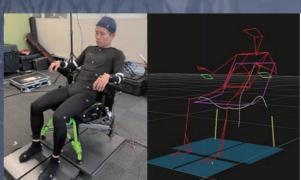


## Integration with Motion Capture System

Tech Gihan's force plates have been integrated with a wide range of motion-capture systems.

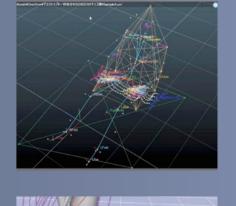
In addition to multi-plate setups, we have experience with not only flat installations but also inclined configurations, and with different sizes and plate types. We also deliver integrated systems that combine force plates with our force sensors and the Seat Tracer.

















Since 1991